

## SeaFEM - Validation Case 13

**Cable attached to a circular rotating plate**



# SeaFEM

**Version  
15.1.0**



## Table of Contents

Chapters	Pag.
Problem description	1
Mesh	3
Results	4
Appendix	6
References	9
Validation Summary	11

## 1 Problem description

The present case aims to simulate a dynamic cable linked to a pulling system that consists on a disc of radius  $r = 0.2$  m. rotating at a fixed constant velocity. In particular two different rotation periods are used for the simulations ( $T_{r1} = 1.25$  s.,  $T_{r2} = 3.5$  s.). The geometrical and parametric configuration of the present analysis reproduces the model proposed by Lindhal and Sjoberg [1] and aims to establish a quantitative comparison against their experimental results. The characteristics of the cable are summarized in the following table.

Cable properties	
Cable length (L)	33.0 m
Apparent weight per unit length (w)	0.18 N/m
Diameter (D)	$2 \times 10^{-3}$ m <sup>2</sup>
Rigidity (E-A)	$1 \times 10^4$ N

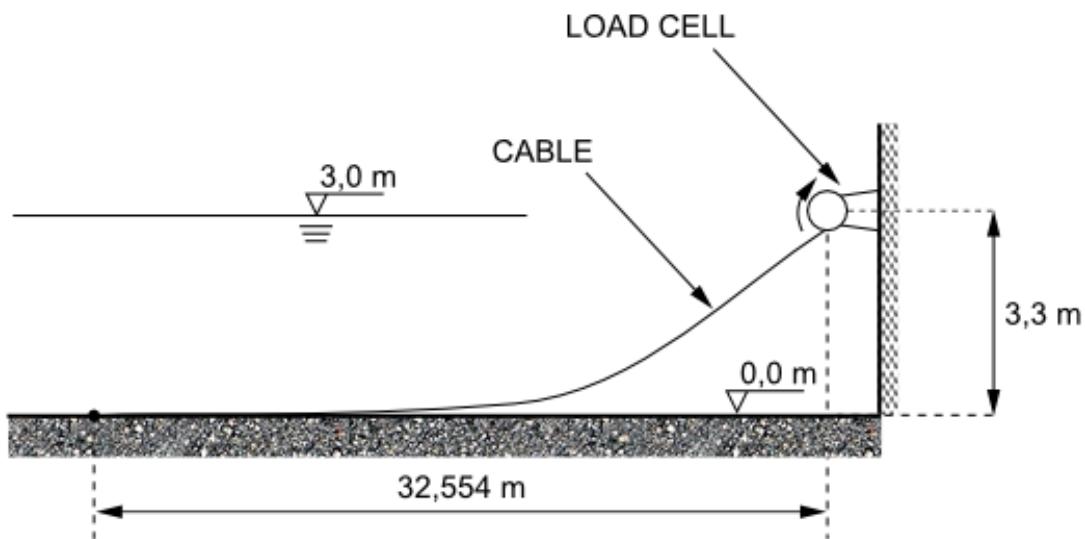
In order to reproduce the effect of the pulling rotation disc, the following functions are used to impose the corresponding movement to the upper end of the cable.

$$x(t) = 0.2 \tanh(0.5t) \left( \cos\left(-\frac{2\pi}{T_r}t + \delta\right) - \cos(\delta) \right),$$

$$y(t) = 0.0,$$

$$z(t) = 0.2 \tanh(0.5t) \left( \sin\left(-\frac{2\pi}{T_r}t + \delta\right) - \cos(\delta) \right).$$

A schema of the problem under consideration is shown in the figure below.



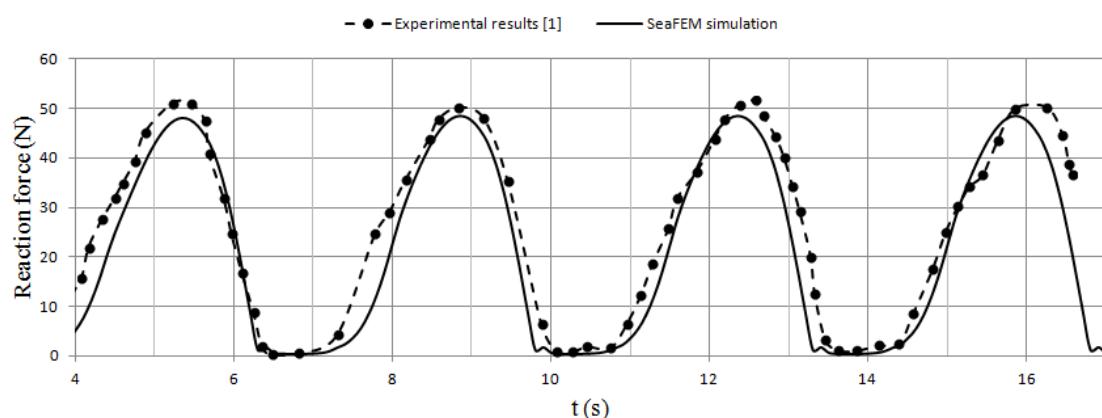
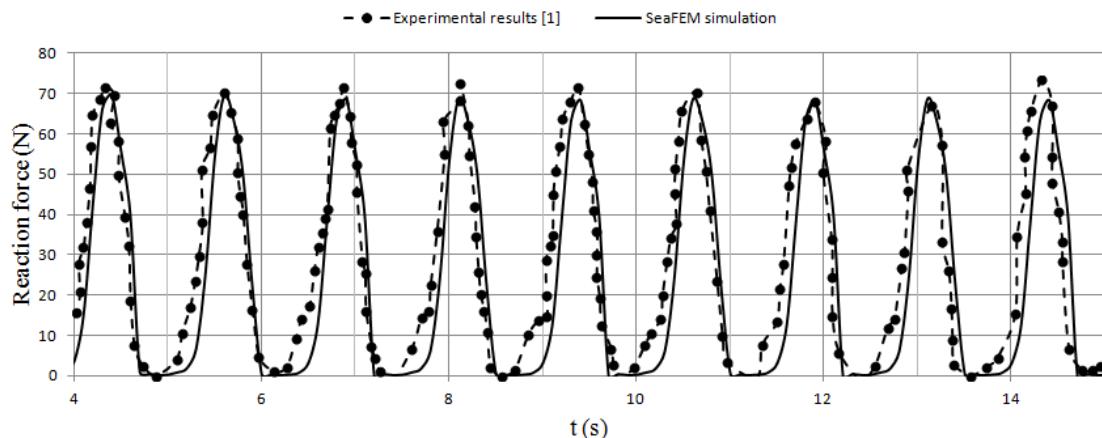
## 2 Mesh

For the present analysis the cable was discretized using 50 linear elements.

The simulations are conducted using a time increment  $\delta t = 0.001$  s. and maintained up to a total simulation time  $t = 60$  s.

### 3 Results

For the sake of validation, the reaction forces at the end of the mooring line are compared against the experimental results in [1]. Such a comparison is shown in the figures below for the two different rotation periods under analysis.





## 4 Appendix

The following code describes the tcl script used for the present analysis. TdynTcl\_CreateMooring procedure is used to create the dynamic cable and to link it to the pulling system. Additionally, the numerical calculation of the diffraction-radiation problem is deactivated. First, the tcl script concerning the case with rotation period  $T = 1.25$  s. is presented. Next, the tcl script for the case with period  $T = 3.5$  s.

```

proc TdynTcl_CreateMooring { } {
    # Validation Case 3
    # Time step suggested for simulation: 0.001 sec.

    # values: Body Type_Mooring Xe[3] Xi [3] w L A S E n_elements damp_ratio_1
    damp_ratio_2

    set seg1 [create_mooring_segment 1 6 0.0 0.0 0.3 -32.554 0.0 -3.0 0.18 33.0
    3.14159e-6 3.1831e9 1 50 0.05 0.05]

    # values: Gk Gc Gu Ms Md Cd Cf Cm alpha_bs bci
    TdynTcl_Configure_Mooring_Segment 1 3.0e6 1.0 0.3 0.0 0.0 0.5 2.5 3.8 0.05 1

    set phi -2.25

    # T = 1.25 sec
    set fun1 [::mather::create_function waves "0.2*tanh(0.5*t)*(cos(-(2*pi/1.25)*t+($phi))-cos($phi));"]
    set fun2 [::mather::create_function waves "0.0;"]
    set fun3 [::mather::create_function waves "0.2*tanh(0.5*t)*(sin(-(2*pi/1.25)*t+($phi))-sin($phi));"]

    TdynTcl_Set_Mooring_Displacement $seg1 $fun1 $fun2 $fun3 0
    TdynTcl_Configure_Analysis Solve_Dif_Rad 0
    TdynTcl_Message "TdynTcl_CreateMooringLine finished!!!" notice
}

proc TdynTcl_CreateMooring { } {
    # Validation Case 3
    # Time step suggested for simulation: 0.001 sec.

    # values: Body Type_Mooring Xe[3] Xi [3] w L A E S n_elements damp_ratio_1

```

```
damp_ratio_2  
set seg1 [create_mooring_segment 1 6 0.0 0.0 0.3 -32.554 0.0 -3.0 0.18 33.0 3.14159e-6  
3.1831e9 1 50 0.025 0.025]  
# values: Gk Gc Gu Ms Md Cd Cf Cm alpha_bs bci  
TdynTcl_Configure_Mooring_Segment 1 3.0e6 1.0 0.3 0.0 0.0 0.5 2.5 3.8 0.01 1  
  
set phi -2.25  
  
# T = 3.5 sec  
set fun1 [::mather::create_function waves "0.2*tanh(0.5*t)*(cos(-(2*pi/3.5)*t+($phi))-  
cos($phi));"]  
set fun2 [::mather::create_function waves "0.0;"]  
set fun3 [::mather::create_function waves "0.2*tanh(0.5*t)*(sin(-(2*pi/3.5)*t+($phi))-  
sin($phi));"]  
  
TdynTcl_Set_Mooring_Displacement $seg1 $fun1 $fun2 $fun3 0  
TdynTcl_Configure_Analysis Solve_Dif_Rad 0  
TdynTcl_Message "TdynTcl_CreateMooringLine finished!!!" notice  
}
```



## 5 References

- [1] Lindahl L., and Sjoberg A. Dynamic analysis of mooring cables. Second international symposium on ocean engineering and ship handling. (1983).



## 6 Validation Summary

CompassFEM version	15.1.0
Tdyn solver version	15.1.0
RamSeries solver version	15.1.0
Benchmark status	Successfull
Last validation date	27/11/2018